

Limits of several variables

Functions of two variables: If three variables x , y and z are so related that the value of z depends upon the values of x and y , then z is called a function of two variables x and y . It is denoted by $z = f(x, y)$.

Limit: If a function $f(x, y)$ has a limit say 'L' at a point (a, b) then it is denoted as

$$\lim_{(x,y) \rightarrow (a,b)} f(x, y) = L.$$

Note:

1. Limit may or may not exist.
2. If a limit exists, it must be unique.

Algebra of Limits: If $\lim_{(x,y) \rightarrow (a,b)} f(x, y) = L$ and $\lim_{(x,y) \rightarrow (a,b)} g(x, y) = M$, then

1. $\lim_{(x,y) \rightarrow (a,b)} f(x, y) \pm g(x, y) = L \pm M$
2. $\lim_{(x,y) \rightarrow (a,b)} f(x, y) \cdot g(x, y) = L \cdot M$
3. $\lim_{(x,y) \rightarrow (a,b)} \frac{f(x, y)}{g(x, y)} = \frac{L}{M}$, provided $M \neq 0$

Partial Derivatives of first order: Let $z = f(x, y)$

- 1. The derivative of z with respect to x , if it exists when x alone varies and y remains constant is called the partial derivative of z with respect to x .**

It is denoted as $\frac{\partial z}{\partial x}$ or $\frac{\partial f}{\partial x}$ or z_x or f_x .

- 2. The derivative of z with respect to y , if it exists when y alone varies and x remains constant is called the partial derivative of z with respect to y .**

It is denoted as $\frac{\partial z}{\partial y}$ or $\frac{\partial f}{\partial y}$ or z_y or f_y .

Partial Derivatives of second order: If $z = f(x, y)$, then the partial derivatives of f_x and f_y gives the second order partial derivatives as follows:

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| <ol style="list-style-type: none"> 1. $\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial x^2} = f_{xx}$ | <ol style="list-style-type: none"> 2. $\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x} = f_{xy}$ |
| <ol style="list-style-type: none"> 3. $\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial x \partial y} = f_{yx}$ | <ol style="list-style-type: none"> 4. $\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial y^2} = f_{yy}$ |

Note: f_{xy} and f_{yx} are called mixed partial derivatives and they are equal if the first partials f_x and f_y are continuous.

Differentiation of a function of a function: If u is a function of t and t is a

function of x and y , then $\frac{\partial u}{\partial x} = \frac{du}{dt} \frac{\partial t}{\partial x}$ and $\frac{\partial u}{\partial y} = \frac{du}{dt} \frac{\partial t}{\partial y}$.

Homogeneous Function: A function $u = f(x, y)$ is said to be homogeneous of degree n if $f(\lambda x, \lambda y) = \lambda^n f(x, y)$.

Similarly a function $u = f(x, y, z)$ is said to be homogeneous of degree n if $f(\lambda x, \lambda y, \lambda z) = \lambda^n f(x, y, z)$.

Euler's Theorem: If $u = f(x, y)$ is a homogeneous function of in variables x and y of degree n , then $x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = nu$.

Similarly, if $u = f(x, y, z)$ is a homogeneous function in three variables of degree n , then $x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = nu$.

Jacobian: If $u = f(x, y)$ and $v = g(x, y)$, then the Jacobian of u and v with respect to x and y is denoted by $J = \frac{\partial(u, v)}{\partial(x, y)}$ and is defined as

$$J = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}.$$

If $u = f(x, y, z)$, $v = g(x, y, z)$ and $w = h(x, y, z)$, then the Jacobian of u , v and w with respect to x , y and z is denoted by $J = \frac{\partial(u, v, w)}{\partial(x, y, z)}$ and is defined as

$$J = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix} = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix}$$

Properties of Jacobian:

(i) If u, v, w are functions of x, y and z with $J = \frac{\partial(u, v, w)}{\partial(x, y, z)}$ & $J' = \frac{\partial(x, y, z)}{\partial(u, v, w)}$,

then $JJ' = 1$.

(ii) If u, v, w are functions of $r(x, y, z), s(x, y, z)$ and $t(x, y, z)$ then

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \frac{\partial(u, v, w)}{\partial(r, s, t)} \times \frac{\partial(r, s, t)}{\partial(x, y, z)}$$