

# Introduction to CALPHAD

# CALPHAD

- CALculation of PHAse Diagrams (CALPHAD)
- Employs classical thermodynamics
- Many applications: Phase equilibrium, thermochemistry, chemical equilibrium, kinetics, microstructure simulation, etc.
- Appropriately renamed as Computational Thermodynamics

- Began as a means to calculate phase diagrams
- Why do we need phase diagrams?
  - Road map for materials design
  - Guideline for materials processing
  - Helps to understand performance related issues ...
- Engineering Materials – multi-component
  - Phase diagrams: difficult to obtain by experiments alone
  - Too many to be determined.
- If we consider 10 elements ( $n=10$ ), then

$$N = \frac{n!}{m!(n-m)!}$$

$n=10$   $m=2$  then require 45 binaries,

$n=10$   $m=3$  then require 120 ternaries,

$n=10$   $m=4$  then require 210 quaternaries are required.

- CALPHAD: a reliable shortcut to generate m-c phase diagrams

# Chronology

- Meijering (1957): Calculated Cr-Cu-Ni phase diagram
- Kaufman (1969) proposed the acronym CALPHAD
- Kaufman & Bernstein (1970): Computer Calculations of Phase diagrams
- Hillert & Staffanson (1971): Sublattice formalism
- CALPHAD Annual Conference: 1973
- Eriksson (1975): SOLGASMIX program
- Pelton (1976): F\*A\*C\*T project started
- Lukas (1977): Lukas program
- CALPHAD Journal: 1977
- Agren, Hillert & Sundman (1981): Compound Energy Formalism
- First version of Thermo-Calc: 1981

- First version of ChemSage: 1987
- Dinsdale (1991) SGTE data for pure elements
- Saunders & Miodownik (1998): CALPHAD: A comprehensive guide
- First version of FactSage (2001)
- Lukas, Fries & Sundman (2007):  
Computational Thermodynamics: The Calphad method

# CALPHAD Vs. Ab initio Methods

## Calphad method

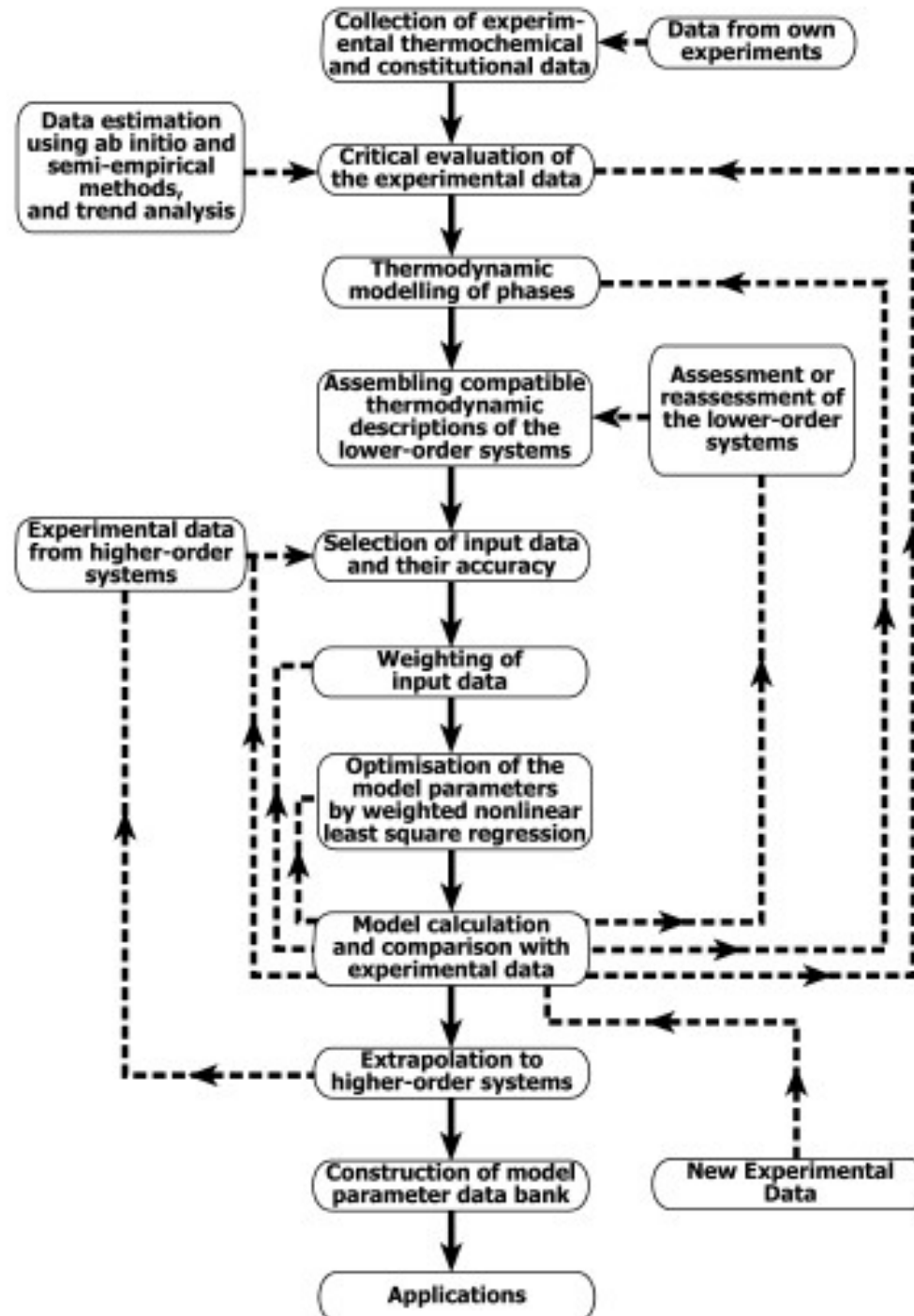
- Classical thermodynamics based
- Phenomenological Gibbs energy models
- Has many adjustable model parameters
- Computationally simple
- Can handle multicomponent-multiphase systems
- Quantitative results, not predictive

## Ab initio methods

- Quantum thermodynamics
- Few/No adjustable parameters
- Can handle only solid phases
- Computationally tedious, even for binaries
- Multicomponent systems are difficult/impossible
- Results are often qualitative, but predictive

Current trend: CALPHAD assisted by ab initio methods

# CALPHAD: Flow chart



# CALPHAD Method

- Gibbs energy model parameters are estimated through a computer assisted modelling procedure (Thermodynamic optimization, Thermodynamic assessment)
- Uses experimental thermochemical and constitutional data as input
- Extrapolative (unlike ab initio methods)  
Unary → Binary → Ternary → Quaternary → Multi-Component
- Experimental data beyond ternary are generally not necessary
- High quality experimental data in lower-order systems are a key to reliable multicomponent thermodynamic descriptions.



# Computer Programs

- Free
  - Lukas program
  - SOLGASMIX
  - Thermo-Calc for academic use
- Commercial
  - Thermo-Calc, FactSage, MTDATA, Pandat, CatCalc
- Application programs
  - DICTRA: Diffusion controlled transformation
  - MICRESS: Microstructure simulation using phase field
  - TC-Prisma, MatCalc: Precipitation simulation



# 1<sup>st</sup> law of thermodynamics

It is the application of the conservation of energy principle to heat and thermodynamic process.

Definition: “The internal energy of an isolated system is constant.”

$$\Delta U = Q - W$$

“The change in internal energy of a system is equal to the heat (Q) added to the system minus the work done by the system (W)”

$$\Delta U = Q - W$$

# 1<sup>st</sup> law of thermodynamics

$$\Delta U = Q - W$$

**Note:** Thermodynamic sign conventions for heat and work:

Process	Convention
Heat added to the system	$Q > 0$
Heat removed from the system	$Q < 0$
Work done by the system	$W < 0$
Work done on the system	$W > 0$

- For closed system, the change in energy is equal to the energy that passes through its boundary as heat or work.
- For isolated system,  $Q = W$        $\Delta U = 0$

## Expansion Work of an Ideal Gas

The gas confined in a cylinder with frictionless piston. Sudden expansion of the gas, undergoes at constant temperature. The work done is

$$w = - \int_{V_1}^{V_2} P dV$$

$$w = -P(V_2 - V_1)$$

# Enthalpy

“Total heat content of the system is called as enthalpy.”

$$H=E+PV$$

“The total heat content of a system at constant pressure is equivalent to the internal energy E plus the PV energy”

$$H=E+PV$$

*Enthalpy is a state function*

*Enthalpy is an extensive property*

*Molar enthalpy is a specific intensive property*

If  $\Delta H$  be the difference of enthalpy of a system in the final state ( $H_2$ ) and that in the initial state ( $H_1$ ),

$$\Delta H = H_2 - H_1$$

Where  $H_1 = E_1 + P_1V_1$  and  $H_2 = E_2 + P_2V_2$

Substituting the values of  $H_2$  and  $H_1$  in the above equation,

$$\begin{aligned}\Delta H &= (E_2 + P_2V_2) - (E_1 + P_1V_1) \\ &= (E_2 - E_1) + (P_2V_2 - P_1V_1) \\ &= \Delta E + (P_2V_2 - P_1V_1)\end{aligned}$$

If  $P$  is constant while the gas is expanding, we can write

$$\Delta H = \Delta E + P\Delta V$$

$$\Delta H = \Delta E + w \quad (w = \text{work})$$

According to the First Law,  $\Delta E = q - w$

where  $q = \text{heat transferred}$

$$\Delta H = q$$

$$\Delta H = q_p$$

where subscript  $p$  means constant pressure.

Thus  $\Delta H$  can be measured by measuring the heat of a process occurring at constant pressure.

If  $\Delta H$  be the difference of enthalpy of a system in the final state ( $H_2$ ) and that in the initial state ( $H_1$ ),

$$\Delta H = H_2 - H_1$$

$\Delta H = +ve$  then  $H_2 > H_1$  and the process is endothermic.

$\Delta H = -ve$  then  $H_1 > H_2$  and the process is exothermic.

Unit: Joule or calorie

**Relation Between  $\Delta H$  and  $\Delta E$ :**

If  $n_1$  moles of gases before reaction, and  $n_2$  moles of gases after it.

Assuming ideal gas behaviour at isothermal condition, then e

$$PV_2 = n_2RT$$

$$P V_1 = n_1RT$$

$$\therefore P (V_2 - V_1) = (n_2 - n_1) RT$$

$$\text{or } P\Delta V = \Delta nRT$$

Then,  $\Delta H = \Delta E + \Delta nRT$



**Heat Capacity:** Amount of heat energy required to raise 1°C of the system

$$C = \frac{q}{m.(T_2 - T_1)}$$

**Specific heat capacity:** Amount of heat energy required to raise 1°C of one mole of the system

$$C = \frac{q}{(T_2 - T_1)}$$

Heat capacity varies with temperature,

$$C = \frac{dq}{dT}$$

Heat and heat capacity are path function.

Unit: JK<sup>-1</sup>mol<sup>-1</sup>

Classification of heat capacity:

- At constant volume  $C_V$
- At constant pressure  $C_p$

According to 1<sup>st</sup> law of thermodynamics,

$$dE=dq-dw$$

Rearrange the above equation,

$$dq=dE+dw=dE+P\Delta V$$

Dividing both sides by  $dT$ ,

$$\frac{dq}{dT} = \frac{dE + PdV}{dT}$$

At constant volume  $dV=0$ ,

$$\frac{dq}{dT} = \frac{dE}{dT}$$

$$C_V = \left( \frac{dE}{dT} \right)_V$$

Thus the heat capacity at constant volume is defined as the rate of change of internal energy with temperature at constant volume.

$$C = \frac{dq}{dT} = \frac{dE + PdV}{dT}$$

w.k.t,  $H=E+PV$

Differentiate the above equation w.r.t T, at constant P, then

$$\left(\frac{dH}{dT}\right)_P = \left(\frac{dE}{dT}\right)_P + P\left(\frac{dV}{dT}\right)_P$$

Comparing the above two equation,

$$\left(\frac{dH}{dT}\right)_P = \left(\frac{dE}{dT}\right)_P + P\left(\frac{dV}{dT}\right)_P = \frac{dq}{dT} = C_P$$

$$\boxed{\left(\frac{dH}{dT}\right)_P = C_P}$$

Thus heat capacity at constant pressure is defined as the rate of change of enthalpy with temperature at constant pressure.

## Relation between $C_p$ and $C_v$

w.k.t. ,

$$C_p = \left( \frac{dH}{dT} \right)_p$$

$$C_v = \left( \frac{dE}{dT} \right)_v$$

By definition,  $H=E+PV$

$$H=E+nRT$$

Differentiate the above equation w.r.t. to  $T$ ,

$$\frac{dH}{dT} = \frac{dE}{dT} + nR$$

The above equation can be written as,

$$C_p = C_v + nR$$

NOTE:  $C_p$  is always greater than  $C_v$ .

## $\Delta E$ expression in terms of heat capacity

For one mole of ideal gas,

$$C_V = \left( \frac{dE}{dT} \right)_V$$

The above equation can be written as,

$$dE = C_V dT$$

$$dE = C_V (T_2 - T_1)$$

For  $n$  moles,

$$dE = nC_V (T_2 - T_1)$$

## $\Delta H$ expression in terms of heat capacity

For one mole of ideal gas,

$$C_P = \left( \frac{dH}{dT} \right)_P$$

The above equation can be written as,

$$dH = C_P dT$$

$$dH = C_P (T_2 - T_1)$$

For  $n$  moles,

$$dH = nC_P (T_2 - T_1)$$

Heat capacity (C) is expressed by an empirical formula (polynomial equation form),

$$C = a + bT + cT^{-1} + dT^{-2}$$

a, b, c and d are co-relation constant

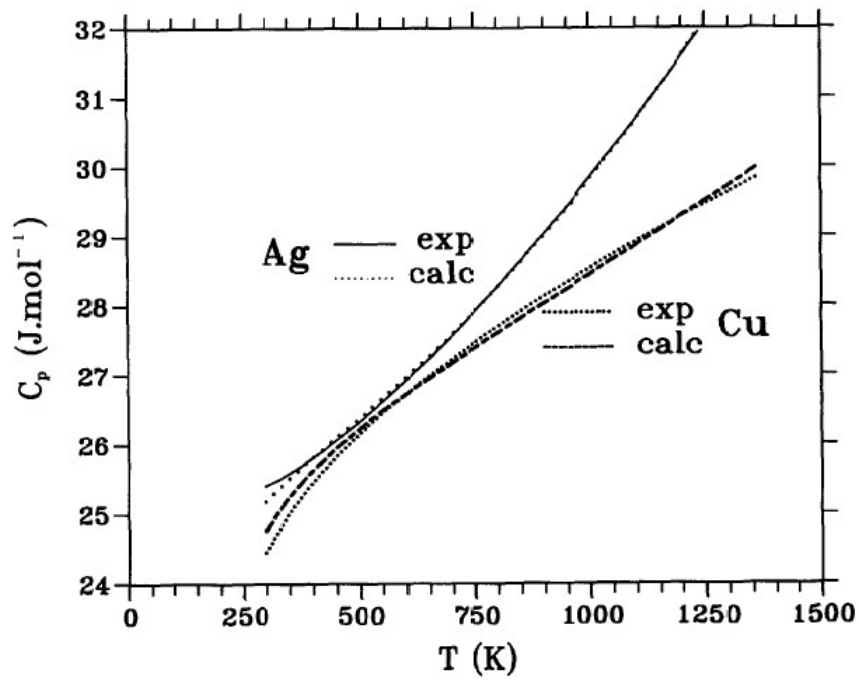


Fig.1 : Calculated and experimental  $C_p$  for fcc Ag and Cu

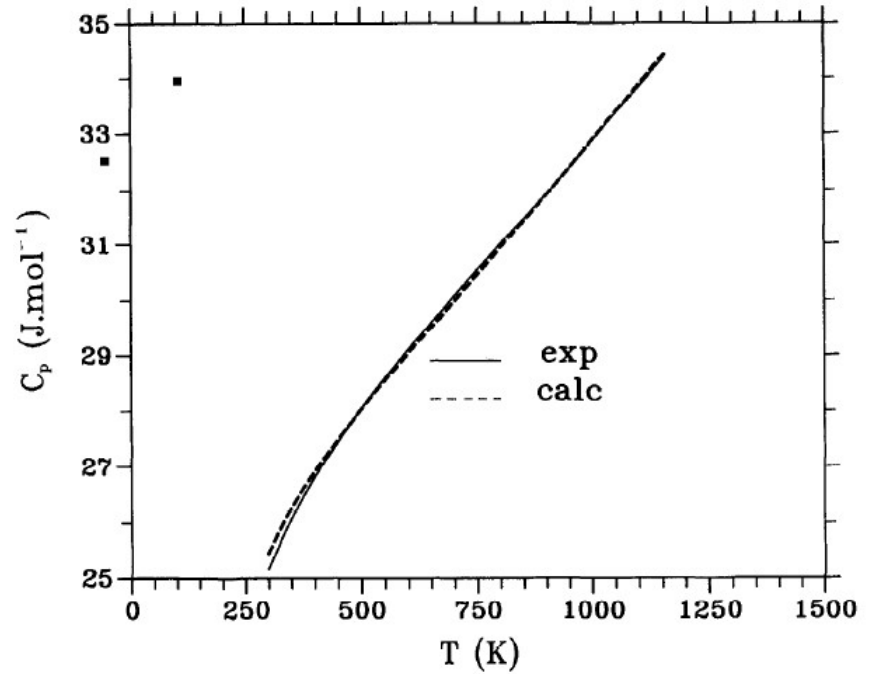


Fig.2 : Calculated and experimental  $C_p$  for hcp Ti



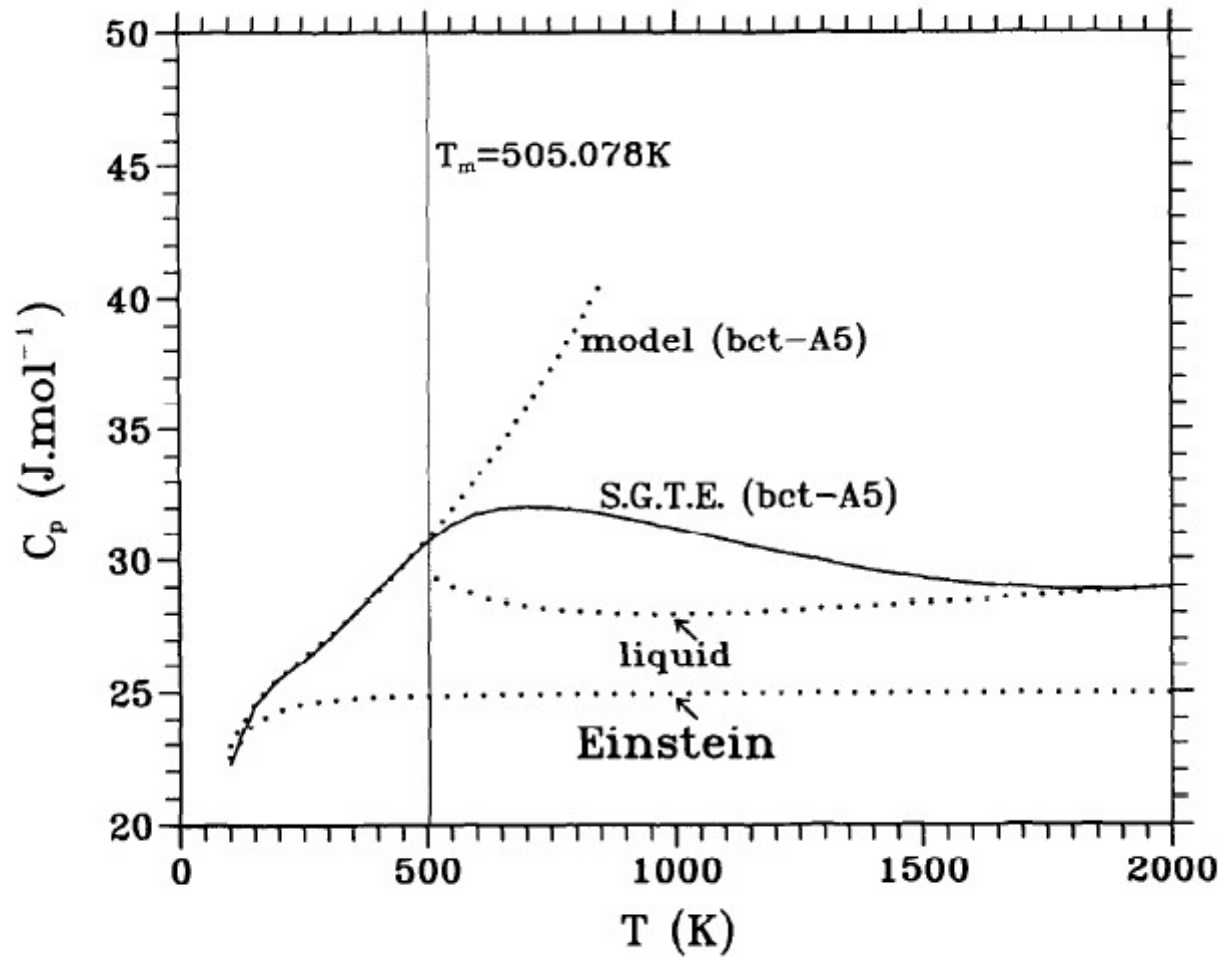


Fig. 3: Calculated and experimental  $C_p$  for bct-A5 and liquid Sn.

The change in enthalpy, entropy and Gibbs energy is expressed as,

$$\Delta H_T = \int_{298.15}^T \Delta C_p dT$$

$$\Delta S_T = \int_{298.15}^T \frac{\Delta C_p}{T} dT$$

$$\Delta G_T = \Delta H - T\Delta S$$

# Gibbs Energy as a Function of Temperature

- At constant P, the heat capacity is represented by,

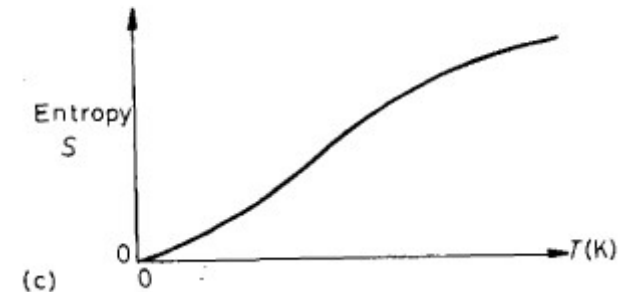
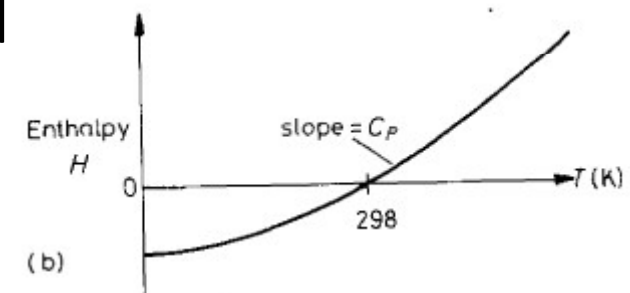
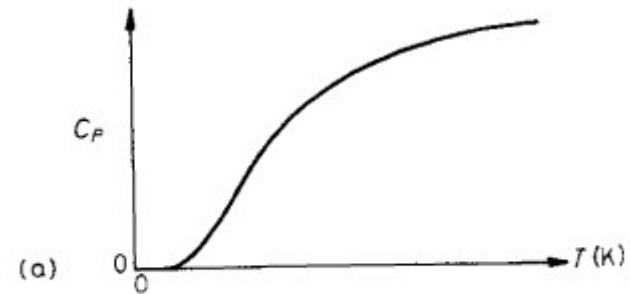
$$\left(\frac{dH}{dT}\right)_P = C_P$$

- The variation of H with T is calculated by integrating the above equation,

$$H = \int_{298}^T C_P dT$$

- The variation of entropy with temperature,

$$\frac{C_P}{T} = \left(\frac{\partial S}{\partial T}\right)_P \quad S = \int_0^T \frac{C_P}{T} dT$$



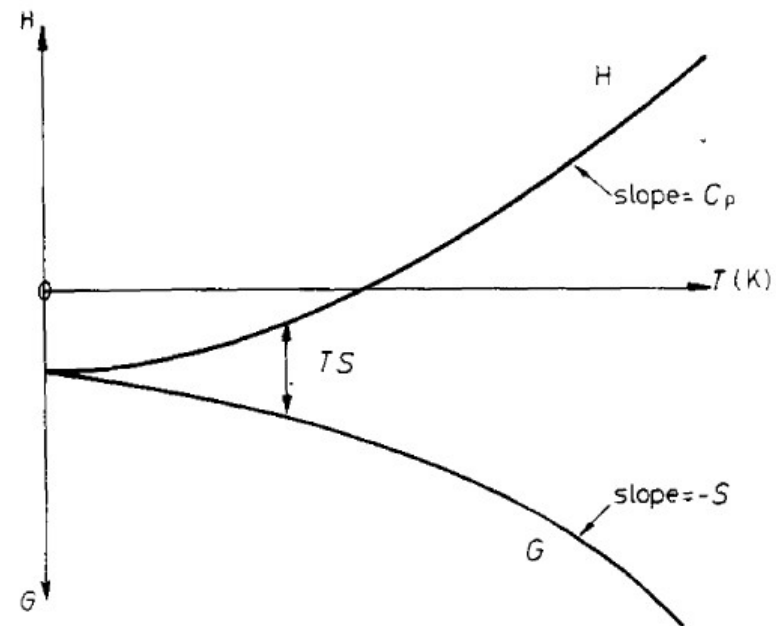
When temperature and pressure vary the changes in G can be obtained by,

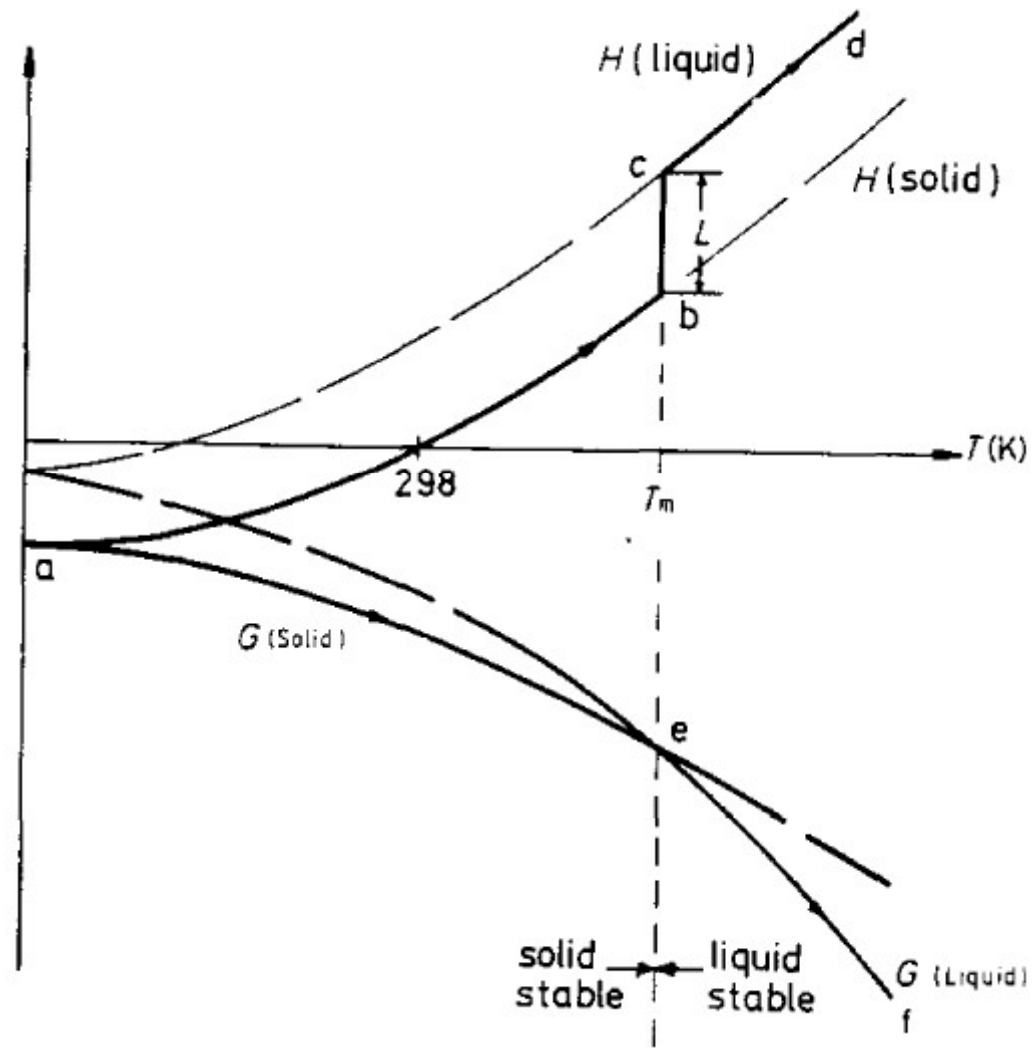
$$dG = -SdT + VdP$$

At constant P,  $dP=0$

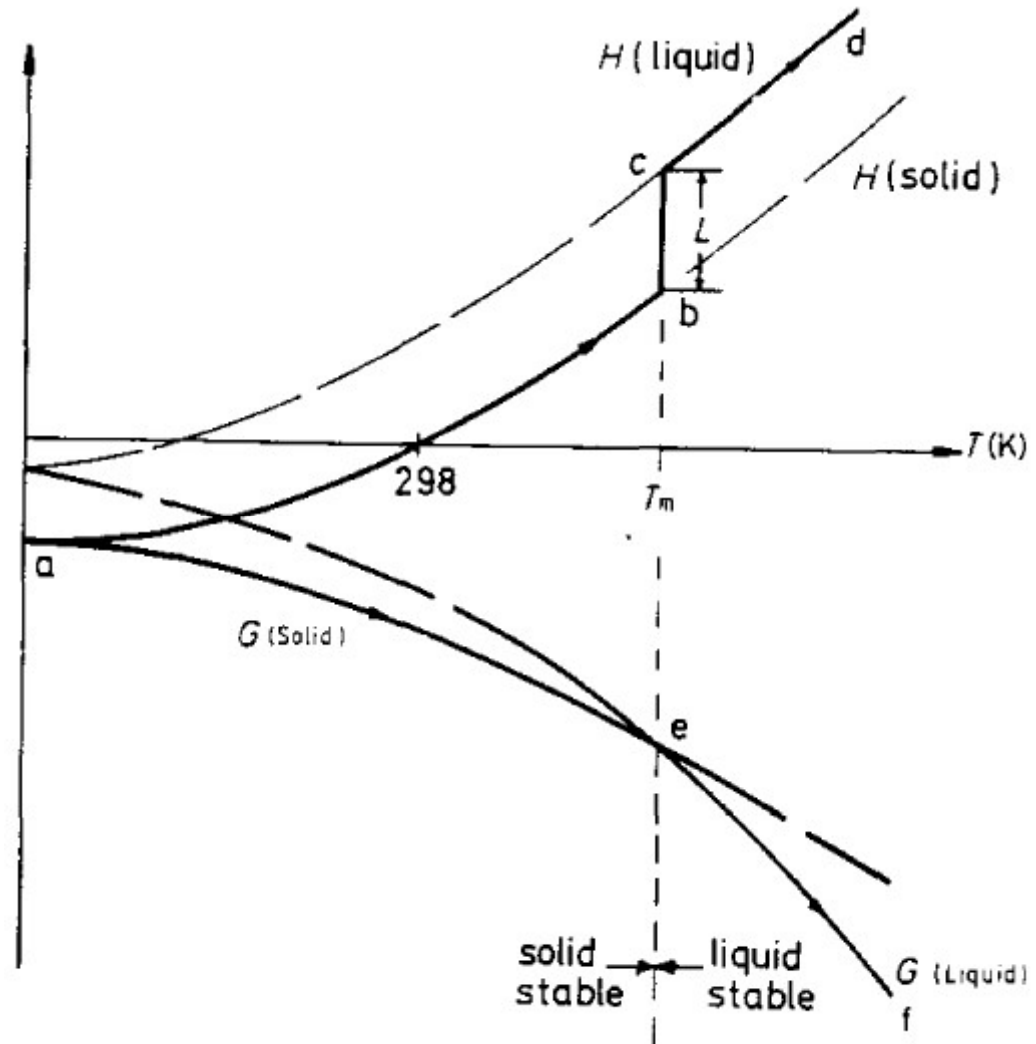
$$\left(\frac{\partial G}{\partial T}\right)_P = -S$$

As T ↑ es, G ↓ es.





- As  $T \uparrow$ es,  $G \downarrow$ es.
- At all  $T$ ,  $H^L > H^S$ .
- At low  $T$ ,  $G^L > G^S$ .
- $S^L > S^S$ , hence  $G^L$  decreases more rapidly with increasing temperature.
- when  $T < T_m$ ,  $G^S < G^L$ . Hence solid phase is stable.
- when  $T > T_m$ ,  $G^L < G^S$ . Hence liquid phase is stable.
- At  $T = T_m$ ,  $G^L = G^S$ , hence both phases are stable.



• At  $T = T_m$ , the heat energy supplied will be used convert the phase. Instead of raising the temperature of the system (latent heat of melting)

# Binary systems : Ideal solutions

- Let us assume that A and B have the same crystal structure and can be mixed in any proportions to make solid solutions.
- Two species in the mixture: consider mole fractions  $X_A$  and  $X_B$

$$X_A + X_B = 1$$

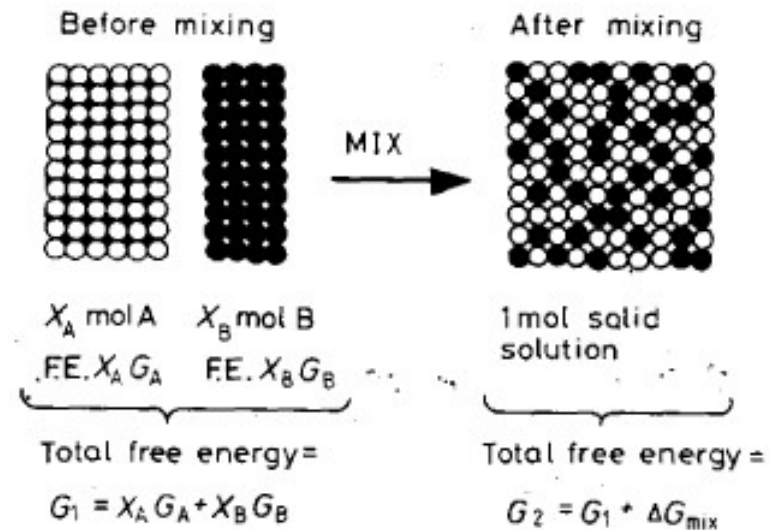
For mixing,

- Bring together  $X_A$  mol of pure A and  $X_B$  mol of pure B

$$G_1 = X_A G_A + X_B G_B$$

- Allow the A and B atoms to mix together

$$G_2 = G_1 + \Delta G_{mix}$$



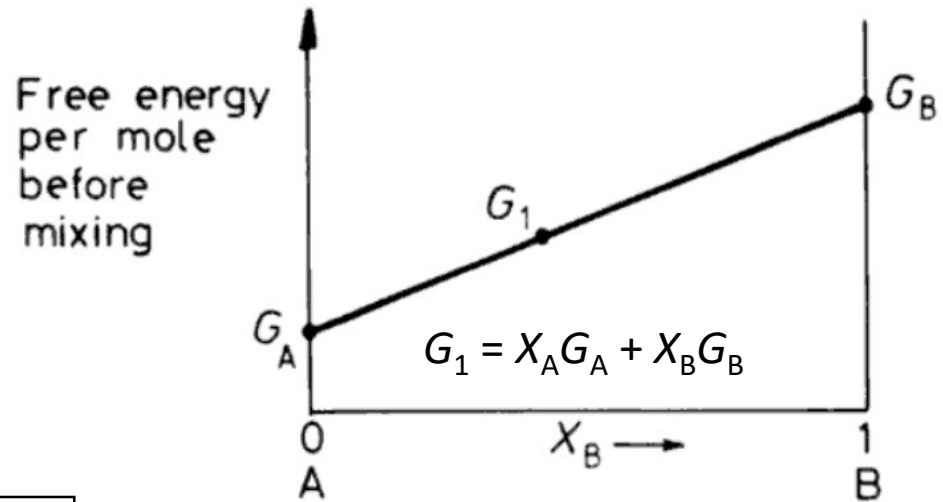
contributions to  $G$  from mixing  
two components together:

1.  $G_1$  – weighted molar average of the two components
2. Free Energy of mixing

$$\Delta G_{\text{MIX}} = \Delta H_{\text{mix}} - T \Delta S_{\text{MIX}}$$

$\Delta H_{\text{mix}}$  is the heat absorbed or evolved during mixing or *heat of solution*

$\Delta S_{\text{MIX}}$  is the entropy difference between the mixed and unmixed states





## Simplest case : Ideal solution : $\Delta H_{\text{MIX}} = 0$

Some assumptions :

1. Free energy change is only due to entropy
2. Species A and B have the same crystal structure (no volume change)
3. A and B mix to form substitutional solid solution

$$S = k_B \ln (\Omega) \quad S \text{ is the configurational entropy}$$

$$\Omega = \frac{(N_A + N_B)!}{N_A! N_B!} \quad \Omega - \text{total number of microstates of system or total number of distinguishable ways of arranging the atoms}$$

Using Stirling's approximation and  $N_a k_B = R$

$$\Delta S_{\text{MIX}} = -R(X_A \ln X_A + X_B \ln X_B)$$

$$\Delta G_{\text{MIX}} = RT(X_A \ln X_A + X_B \ln X_B)$$

Mixing components lowers the free energy!

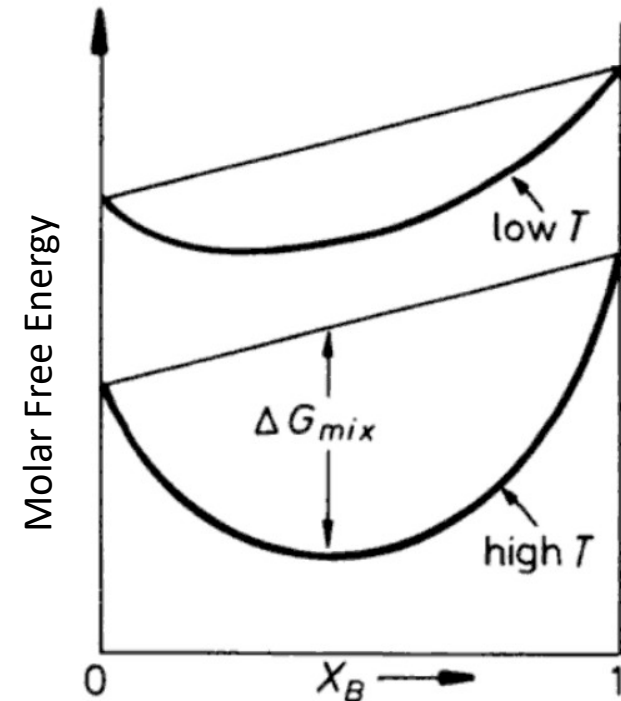
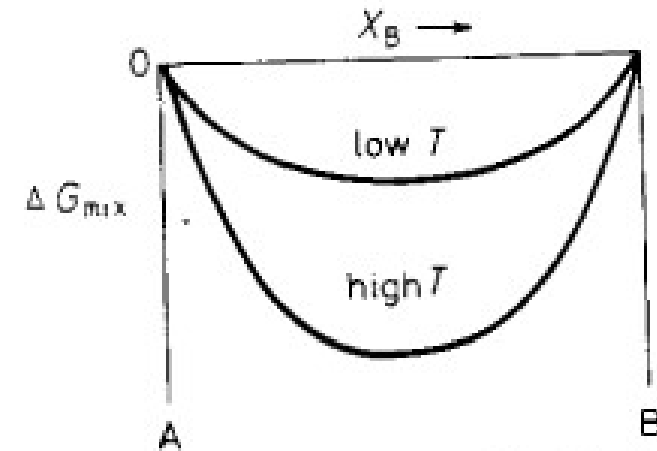
$$\Delta G_{\text{MIX}} = RT(X_A \ln X_A + X_B \ln X_B)$$

Mixing components lowers the free energy!

$$G_2 = G_1 + \Delta G_{\text{mix}}$$

Total Gibbs energy of the systems is

$$G_2 = X_A G_A + X_B G_B + RT(X_A \ln X_A + X_B \ln X_B)$$



## Chemical potential

When small quantity  $dn_A$  mole added to A, then the change in Gibbs energy become,

$$dG' = \mu_A dn_A \quad (T, P, n_B \text{ constant})$$

The proportionality constant  $\mu_A$  is called as partial molar Gibbs energy or chemical potential.

$$\mu_A = \left( \frac{\partial G'}{\partial n_A} \right)_{T, P, n_B}$$

Then two component contribution at constant T and P,

$$dG' = \mu_A dn_A + \mu_B dn_B$$

The above equation can be written as,

$$G = \mu_A X_A + \mu_B X_B \quad \text{J mol}^{-1}$$

The change in Gibbs energy with respect T, P and mole, can written as,

$$dG' = -SdT + VdP + \mu_A dn_A + \mu_B dn_B$$

$$G = \mu_A X_A + \mu_B X_B \quad \text{J mol}^{-1}$$

Total Gibbs energy of ideal solution is,

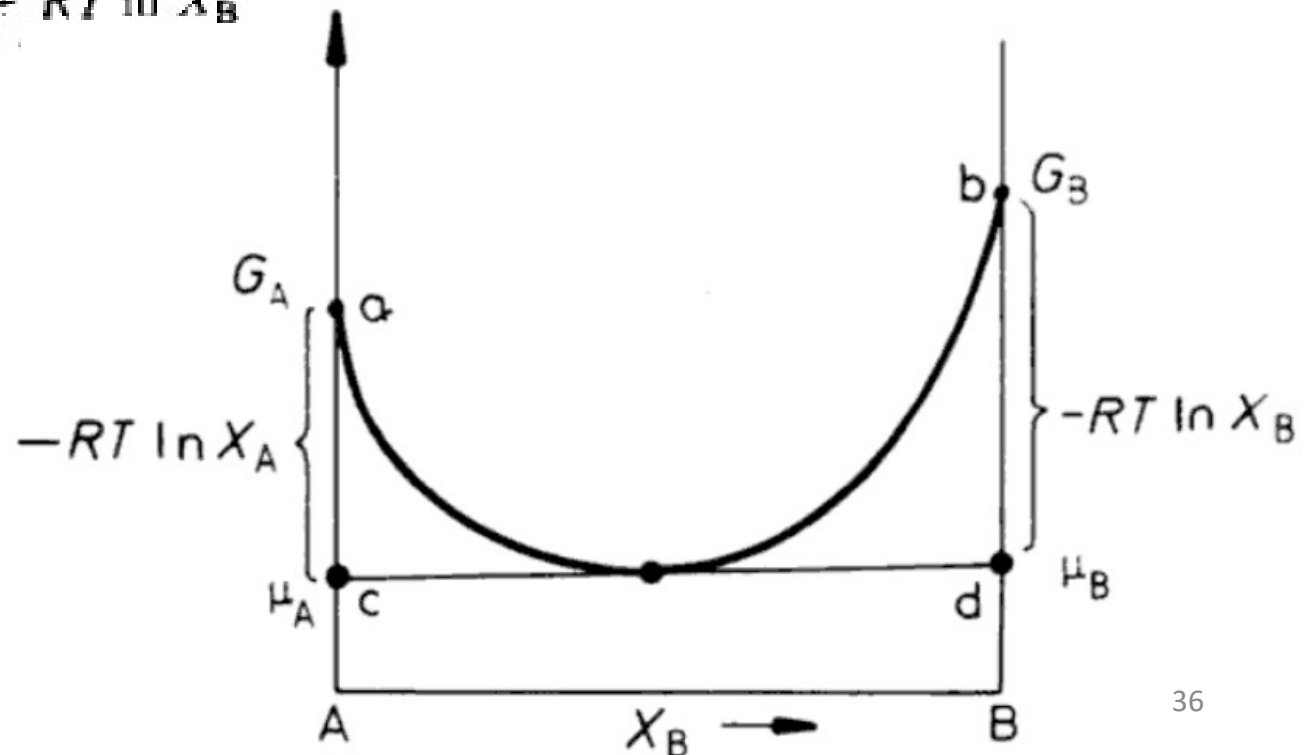
$$G_2 = X_A G_A + X_B G_B + RT(X_A \ln X_A + X_B \ln X_B)$$

Simplified equations for an ideal liquid:

$$\mu_A = G_A + RT \ln X_A$$

$$\mu_B = G_B + RT \ln X_B$$

The relationship between the free energy curve and chemical potentials for ideal solution



## Binary systems : Regular solutions

$\Delta H_{\text{MIX}} \neq 0$  i.e. internal energy of the system must be considered

In a binary, 3 types of bonds: A-A, B-B, A-B of energies  $\epsilon_{AA}$ ,  $\epsilon_{BB}$ ,  $\epsilon_{AB}$

The internal energy of the solution  $E$  depend on the number of bonds of each type  $P_{AA}$ ,  $P_{BB}$  and  $P_{AB}$ , such that,

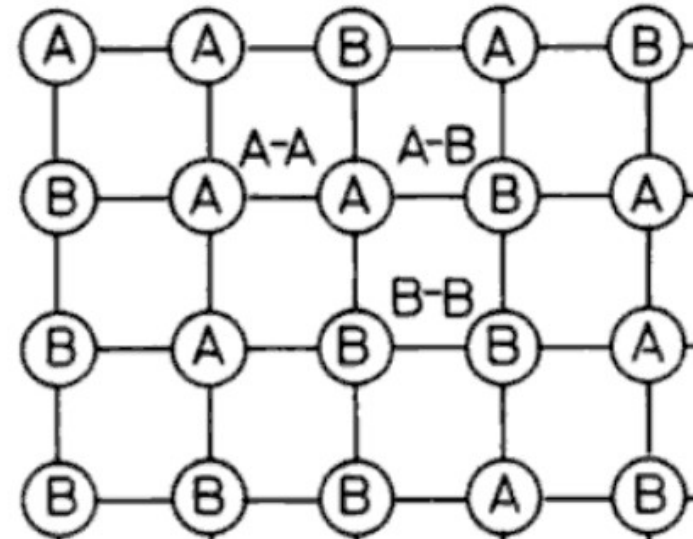
$$E = P_{AA}\epsilon_{AA} + P_{BB}\epsilon_{BB} + P_{AB}\epsilon_{AB}$$

Then,

$$\Delta H_{\text{mix}} = P_{AB}\epsilon$$

$$\epsilon = \epsilon_{AB} - \frac{1}{2}(\epsilon_{AA} + \epsilon_{BB})$$

If  $\epsilon = 0$ ,  $\Delta H_{\text{mix}} = 0$  the solution becomes ideal solution.



For completely random solution,

$$P_{AB} = N_a z X_A X_B \text{ bonds mol}^{-1}$$

where  $N_a$  is Avogadro's number and  $Z$  is the number bonds per atom

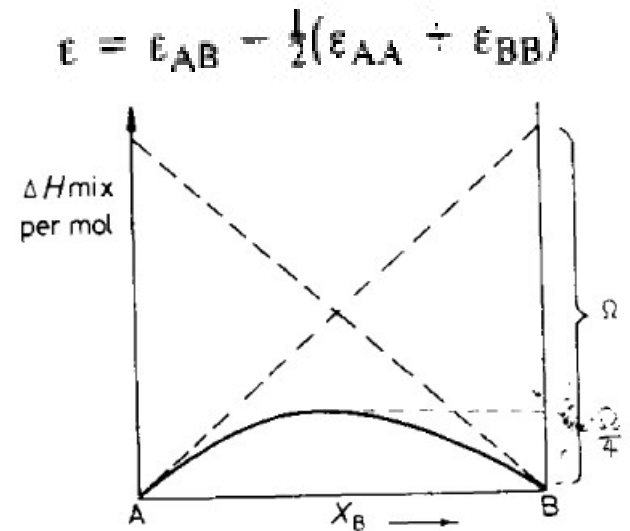
$$\boxed{\Delta H_{MIX} = \Omega X_A X_B} \quad \text{Where } \Omega = N_a z \epsilon,$$

If  $\Omega < 0 \Rightarrow$  A-B bonding preferred

If  $\Omega > 0 \Rightarrow$  AA, BB bonding preferred

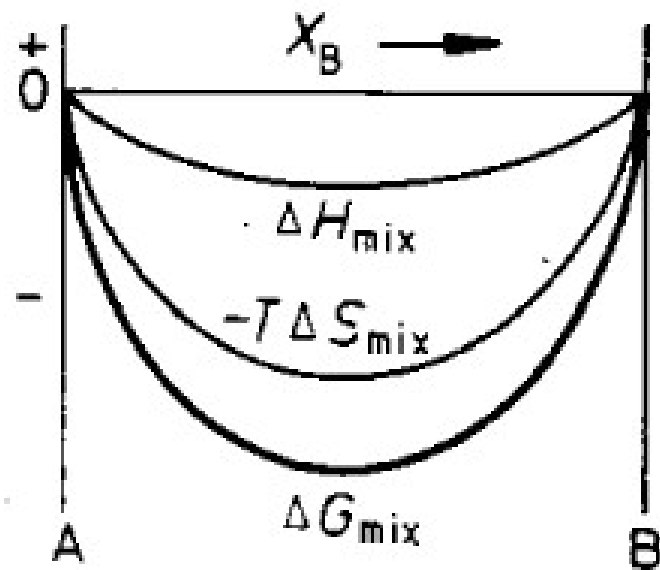
$$\boxed{\Delta G_{MIX} = \Delta H_{MIX} + RT(X_A \ln X_A + X_B \ln X_B)}$$

$$\Delta G_{mix} = \underbrace{\Omega X_A X_B}_{\Delta H_{mix}} + \underbrace{RT(X_A \ln X_A + X_B \ln X_B)}_{-T\Delta S_{mix}}$$

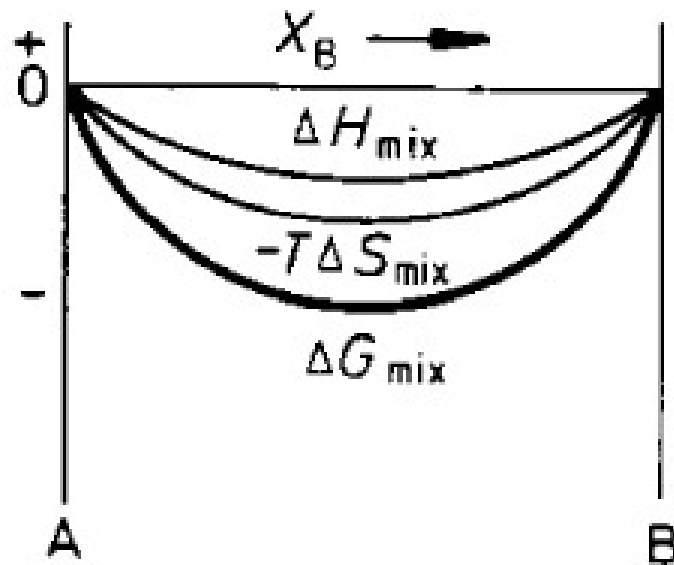


## Effect of $\Delta H_{\text{mix}}$ and $T$ on $\Delta G_{\text{mix}}$

$\Omega < 0$ , then  $\Delta H_{\text{mix}} < 0 \rightarrow$  exothermic reactions

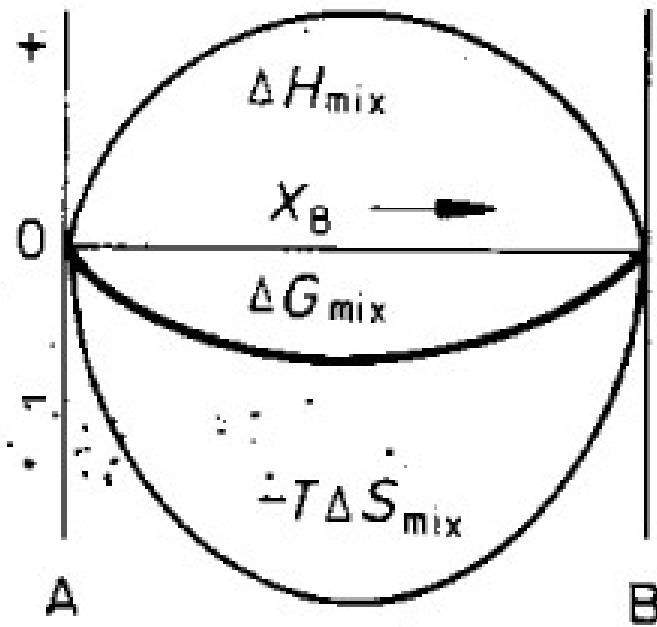


(a)  $\Omega < 0$ , high  $T$

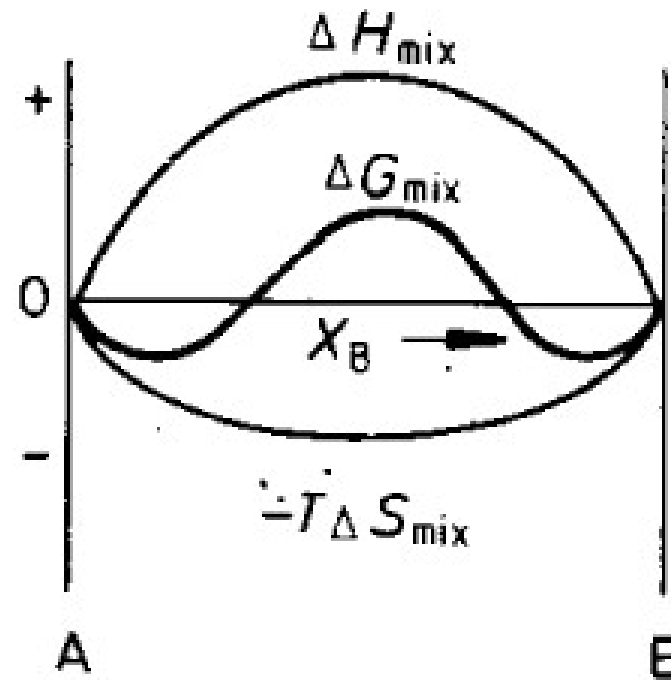


(b)  $\Omega < 0$ , low  $T$

$\Omega > 0$ , then  $\Delta H_{\text{mix}} > 0 \rightarrow$  exothermic reactions



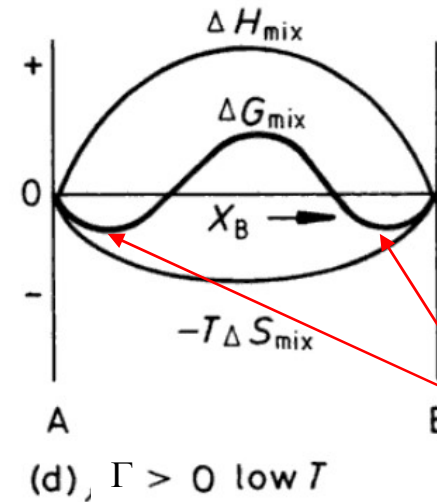
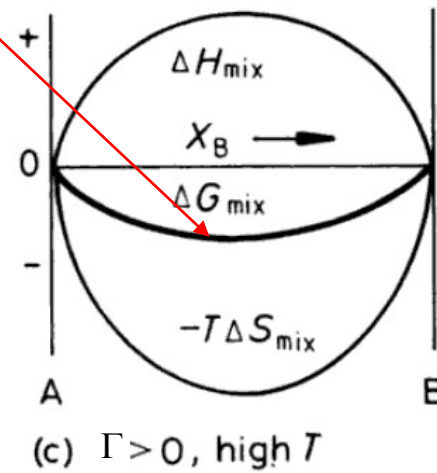
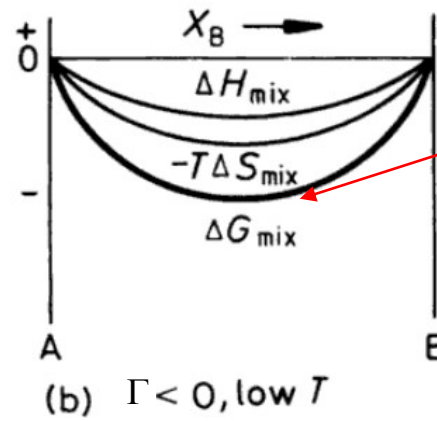
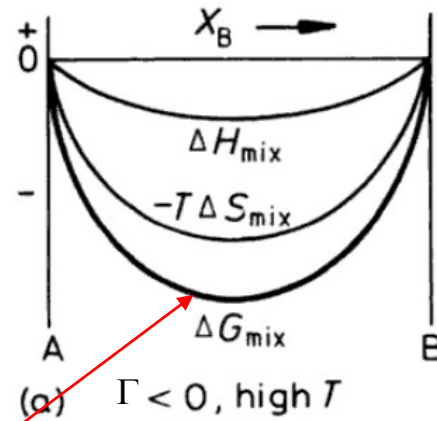
(c)  $\Omega > 0$ , high  $T$



(d),  $\Omega > 0$  low  $T$



Free energy curves for various conditions:



Mixing always occurs at high Temp. despite bonding

Mixing if A and B atoms bond

A and B atoms repel  
Phase separation in to 2 phases.

The Gibbs energy of the alloy in regular solution can be written as

$$G = X_A G_A + X_B G_B + \Omega X_A X_B + RT(X_A \ln X_A + X_B \ln X_B)$$

Using the relationship,  $X_A X_B = X_A^2 X_B + X_B^2 X_A$

The regular solutions represented as,

$$\mu_A = G_A + \Omega(1 - X_A)^2 + RT \ln X_A$$

and

$$\mu_B = G_B + \Omega(1 - X_B)^2 + RT \ln X_B$$

.

**Activity:** Escaping tendency of an atom to leave the solution.

$$a_A \propto X_A$$

$$a_A = \gamma_A X_A$$

$\gamma_A$  is activity coefficient

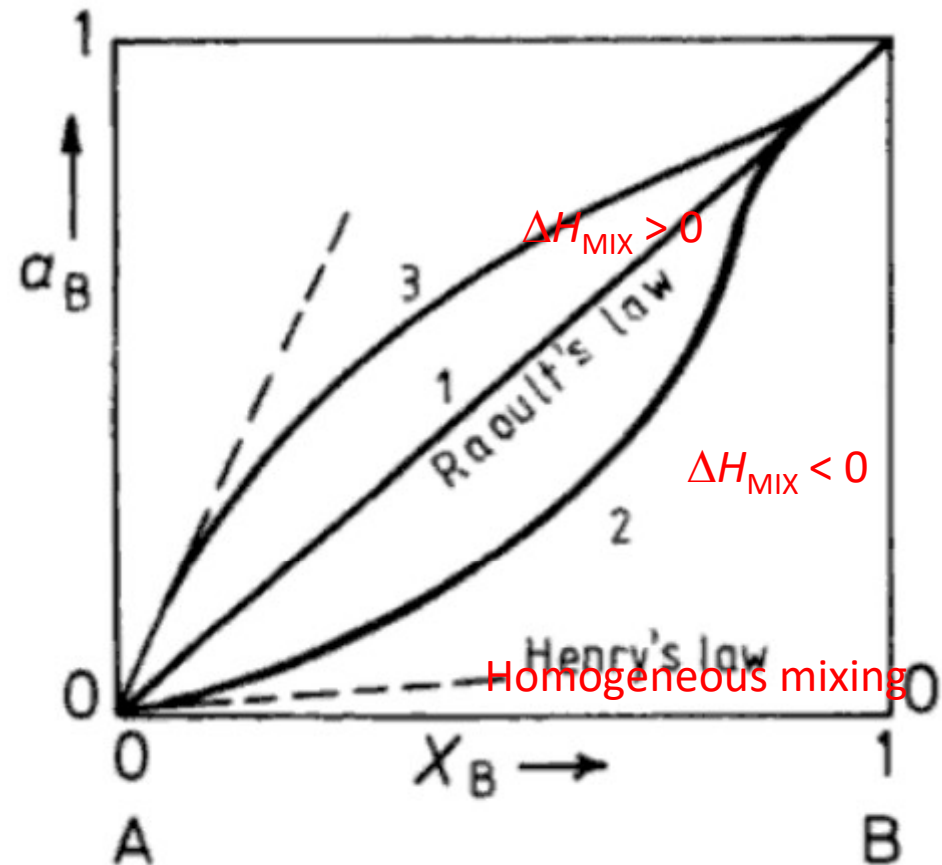
For Ideal solution,  $\gamma_A = 1$  therefore  
(line 1)

$$\gamma_A = \frac{a_A}{X_A} = 1 \quad \text{Raoult's law}$$

$$a_A = X_A$$

If  $\Delta H_{\text{mix}} > 0$  or  $\Delta H_{\text{mix}} < 0$ , then it deviates take path 3 and 1 respectively .

For dilute solution,  $\gamma_A = \frac{a_A}{X_A} = \text{Constant}$  **Henry's law**

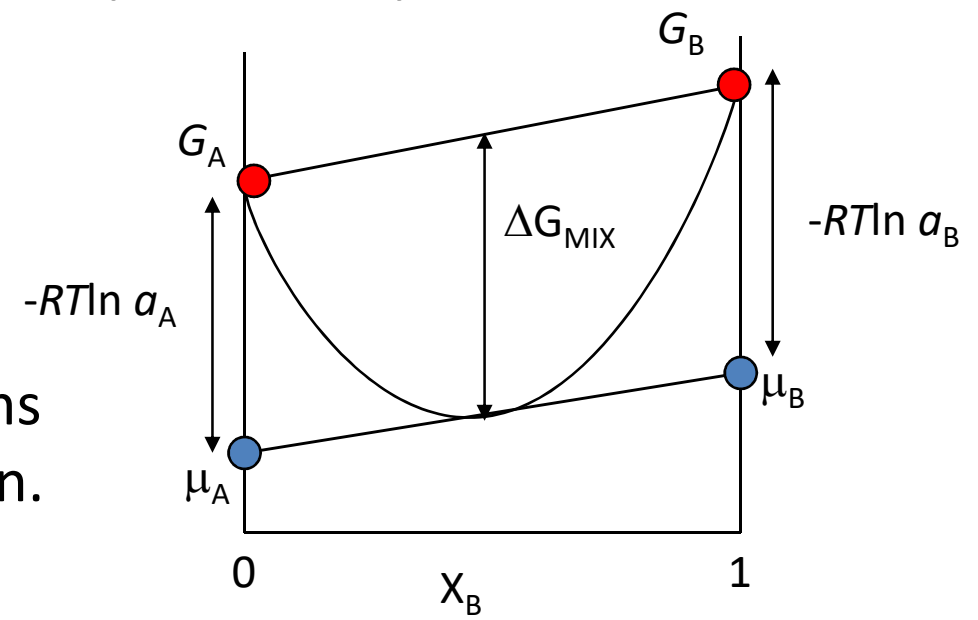


Activity is simply related to chemical potential by:

$$\mu_A = G_A + RT \ln a_A$$

$$\mu_B = G_B + RT \ln a_B$$

Low activity means that the atoms are reluctant to leave the solution.



$$\ln \left( \frac{a_A}{X_A} \right) = \frac{\Omega}{RT} (1 - X_A)^2 \quad \ln \left( \frac{a_B}{X_B} \right) = \frac{\Omega}{RT} (1 - X_B)^2$$

i.e. For homogeneous mixing,  $\Omega < 0 \Rightarrow a_A < X_A$  and  $a_B < X_B$

So the activity is the tendency of a component to leave solution

For low concentrations of B ( $X_B \ll 1$ )

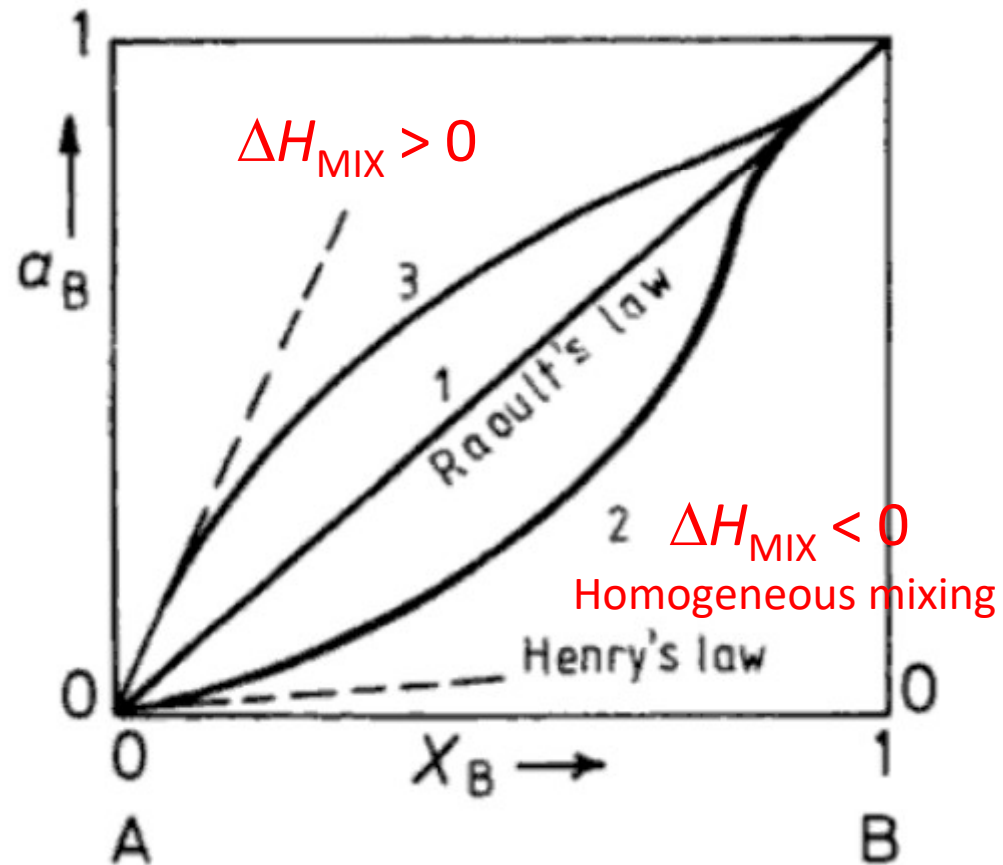
$$\gamma_B = \frac{a_B}{X_B} \approx \text{const.}$$

Henry's Law (or everything dissolves)

And...

$$\gamma_A = \frac{a_A}{X_A} \approx 1$$

Raoult's Law



## Gibbs energy diagram of Isothermal Solid Solution

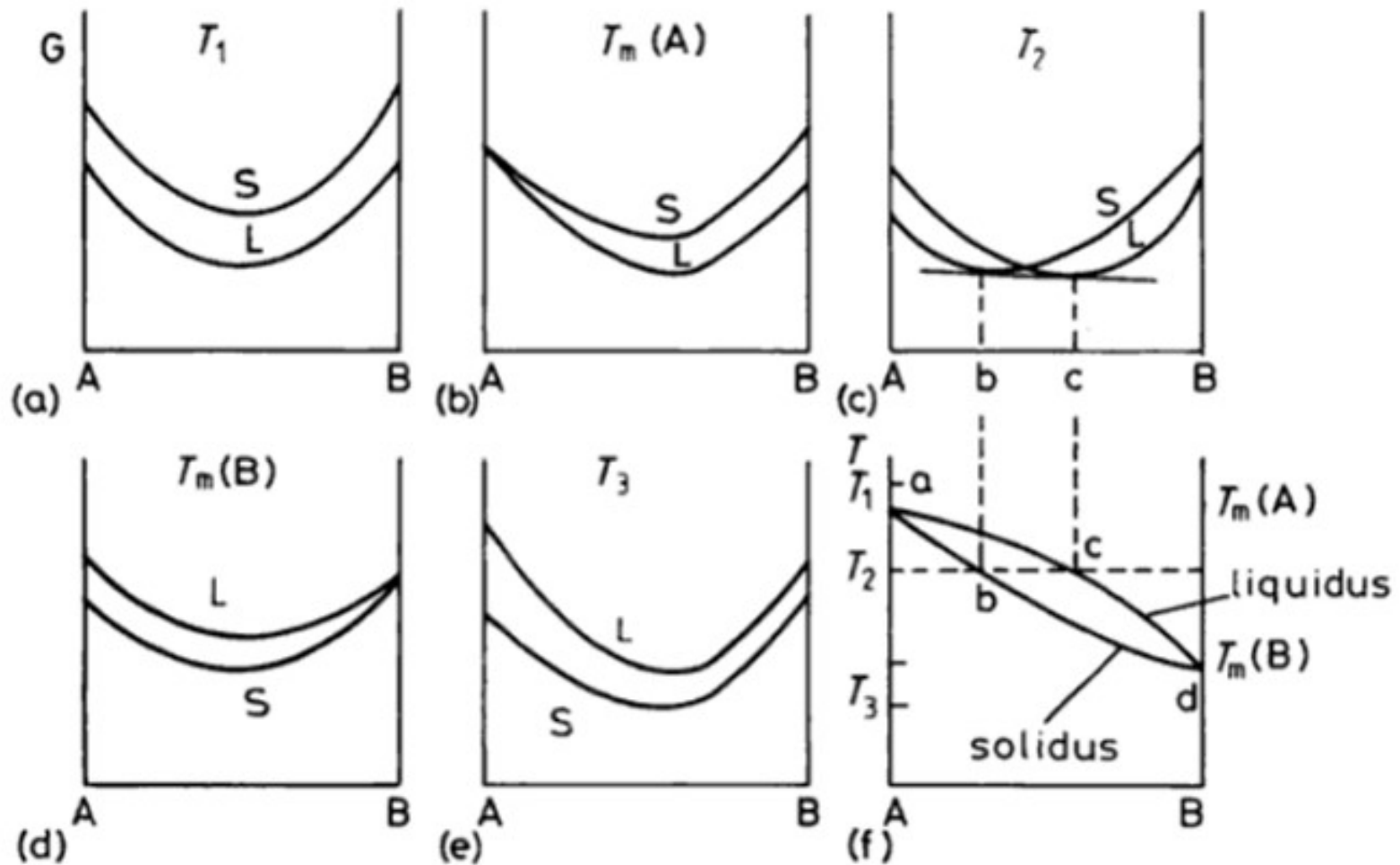
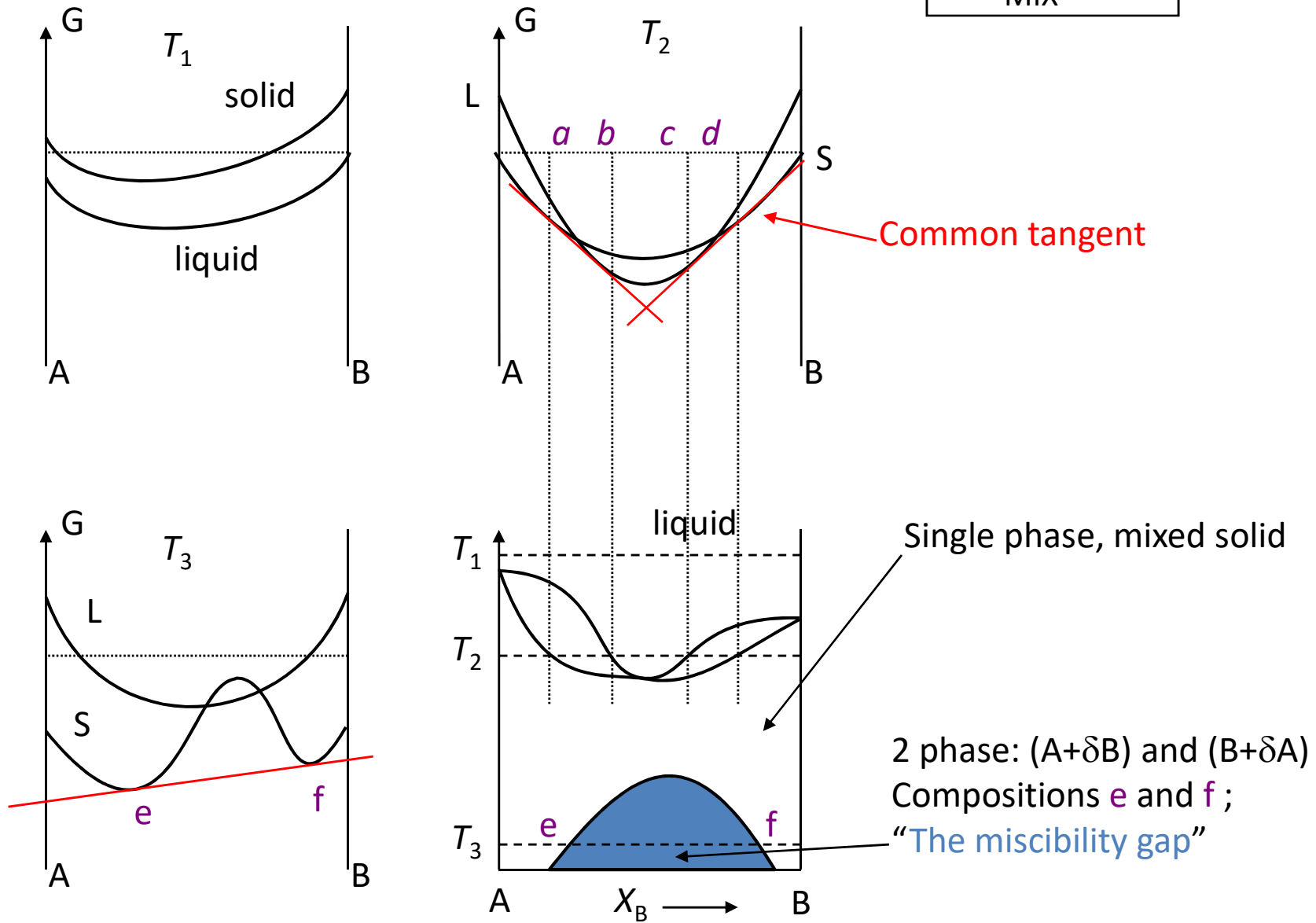


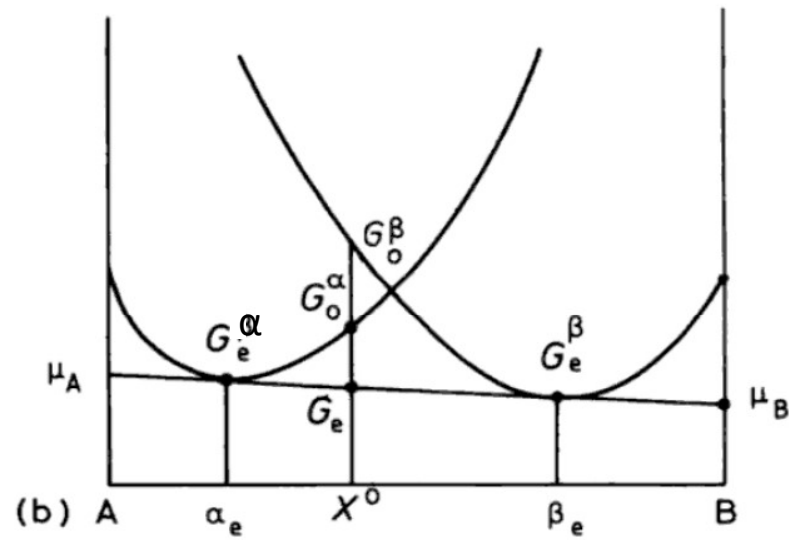
Fig. 1.29 The derivation of a simple phase diagram from the free energy curves for the liquid (L) and solid (S).

## 5. Binary phase diagrams : The Miscibility gap

$$\Delta H_{\text{MIX}} > 0$$



## Equilibrium in heterogenous systems





## Equilibrium in heterogeneous systems

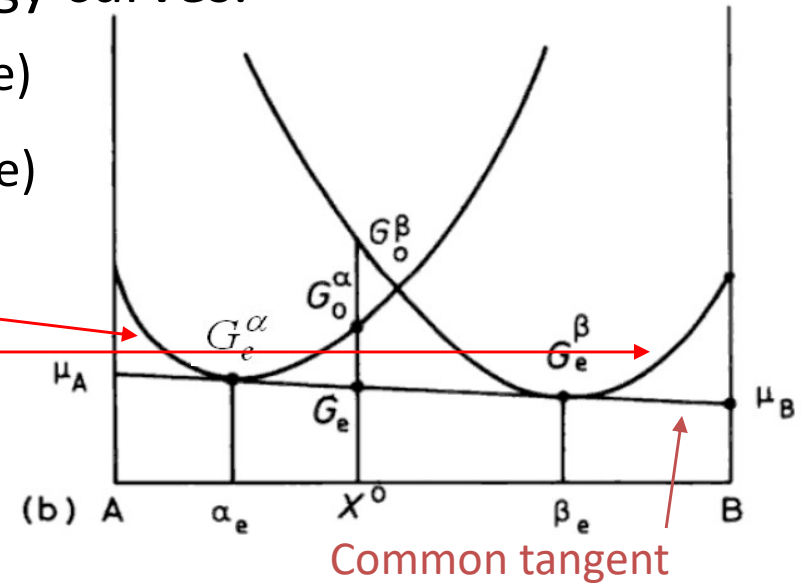
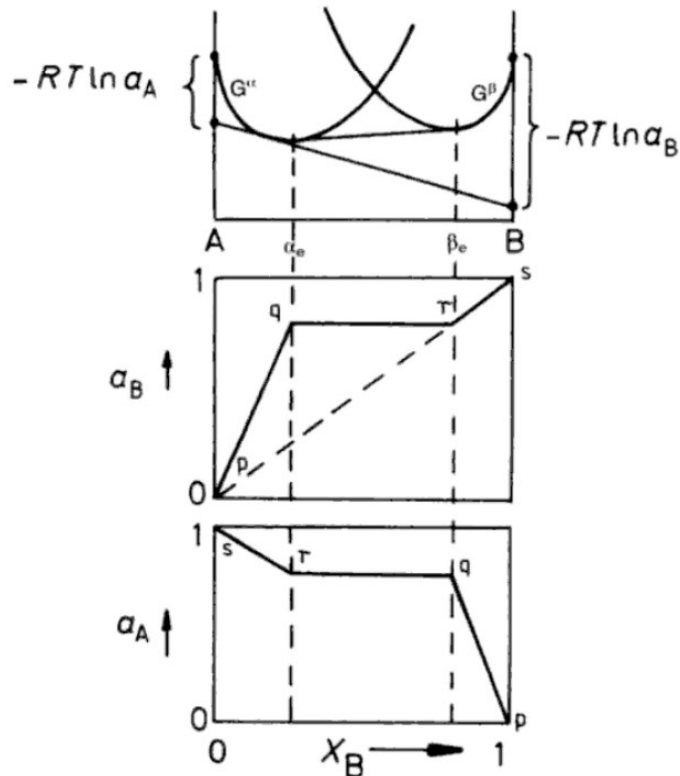
For systems with phase separation ( $\alpha$  and  $\beta$ ) of two stable structures (e.g. *fcc* and *bcc*), we must draw free energy curves.

$G^\alpha$  is the curve for A and B in *fcc* structure ( $\alpha$  phase)

$G^\beta$  is the curve for A and B in *bcc* structure ( $\beta$  phase)

For:  $X^0 < \alpha_e \rightarrow \alpha$  phase only

$X^0 > \beta_e \rightarrow \beta$  phase only



If  $\beta_e < X^0 > \alpha_e$  then minimum free energy is  $G_e$   
 And two phases are present. When two phases exist in equilibrium, the activities of the components must be equal in the two phases:

$$a_A^\alpha = a_A^\beta$$

$$a_B^\alpha = a_B^\beta$$

## Binary (two component) systems : *Ordered phases*

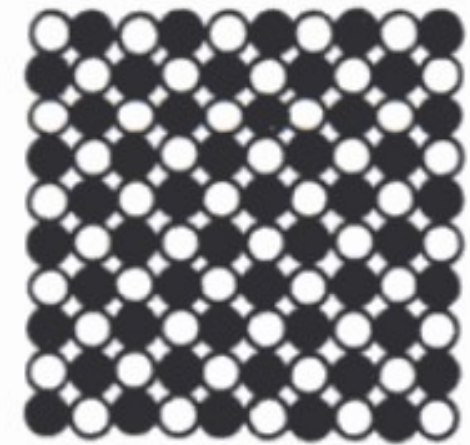
Previous model gross oversimplification : need to consider size difference between A and B (strain effects) and type/strength of chemical bonding between A and B.

*Systems with strong A-B bonds can form Ordered and/or intermediate phases*

Ordered phases occur for (close to) integer ratios.

i.e. 1:1 or 3:1 mixtures.

But entropy of mixing is very small so increasing temperature can disorder the phase. At some critical temperature, long range order will disappear.

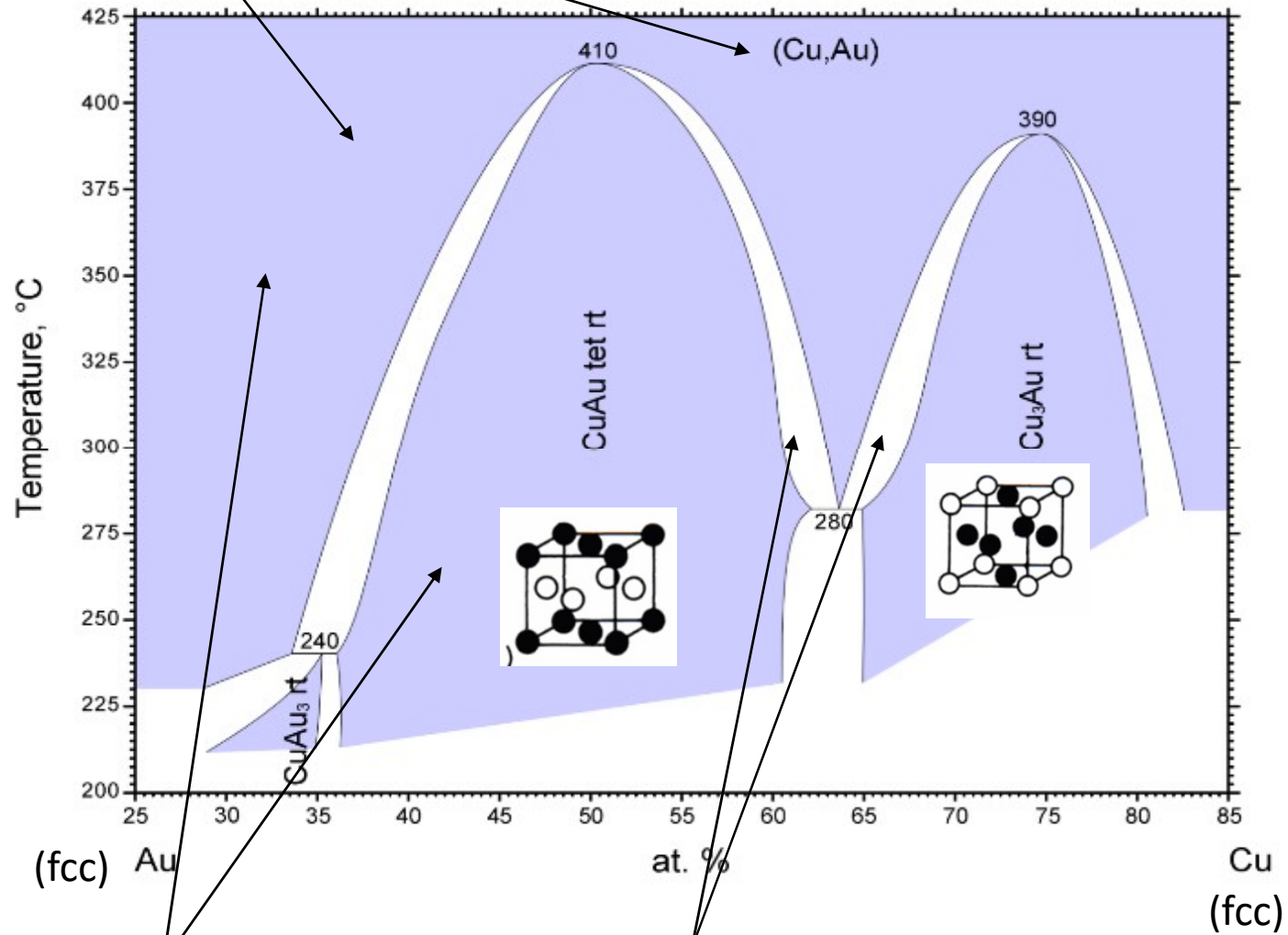


Ordered substitutional

*Ordered structures can also tolerate deviations from stoichiometry. This gives the broad regions on the phase diagram*

# The Copper-Gold system

Random mixture



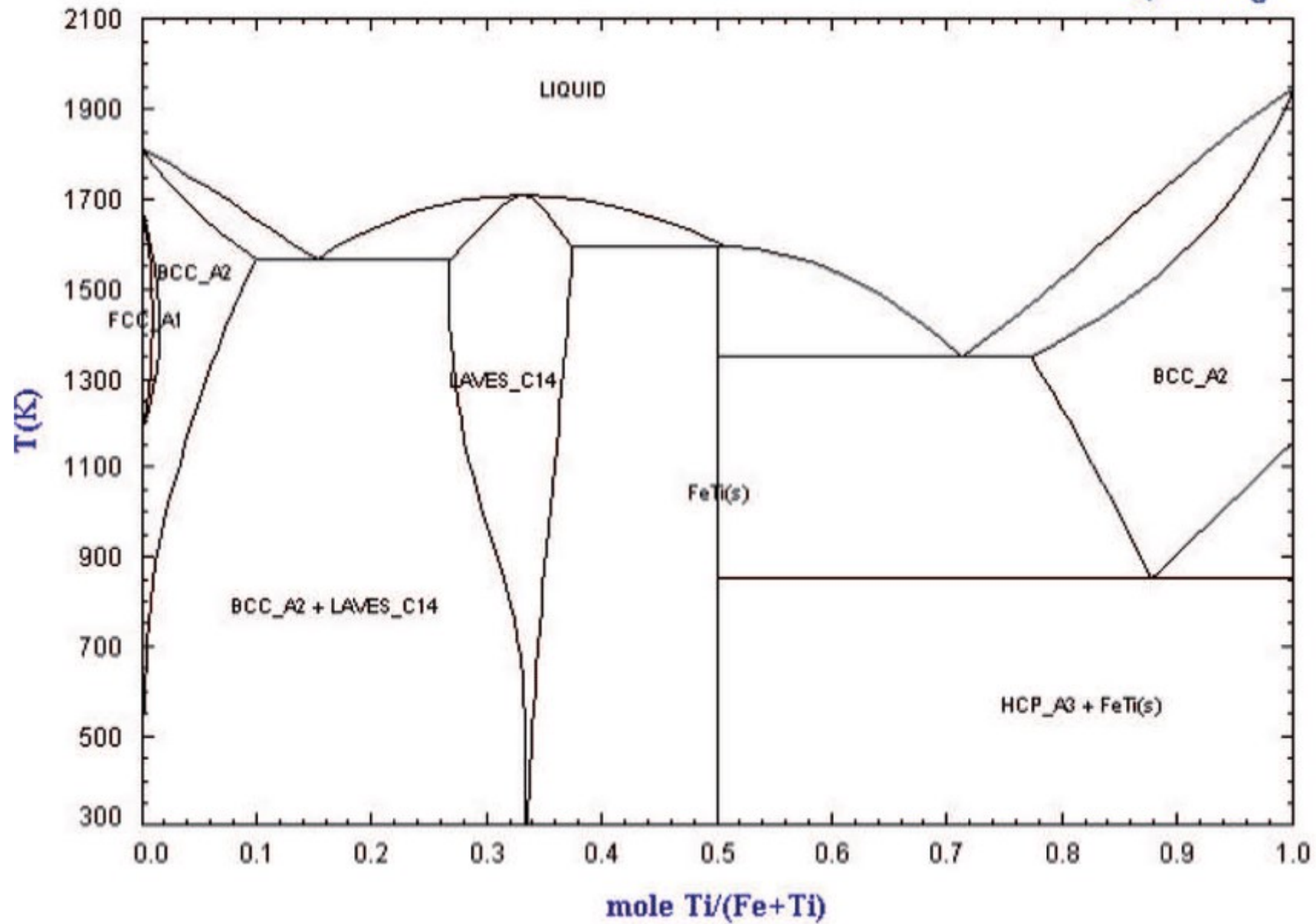
Single phases

Mixed phases

N.B. Always read the legend!!! (blue is not always 'single phase')<sup>51</sup>

# Fe - Ti

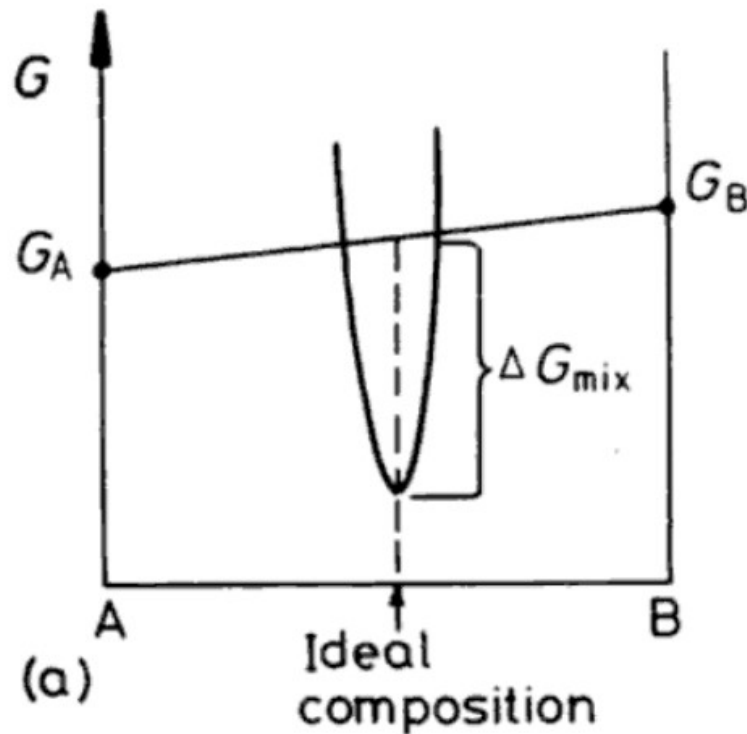
Data from SGTE 2007 alloy database



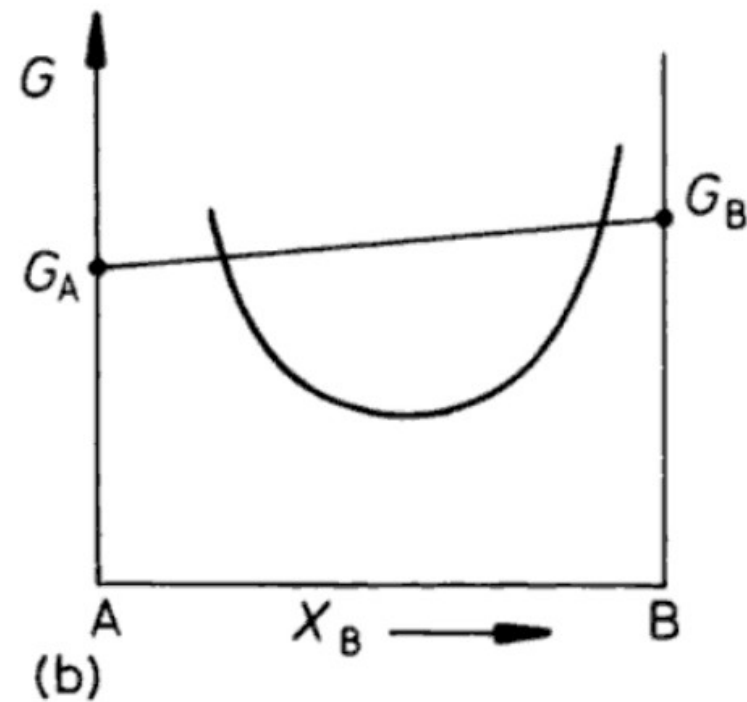
An *intermediate* phase is a mixture that has different structure to that of either component

Range of stability depends on structure and type of bonding (Ionic, metallic, covalent...)

*Intermetallic* phases are intermediate phase of integer stoichiometry (e.g. Ni<sub>3</sub>Al) and congruent melting point



Narrow stability range



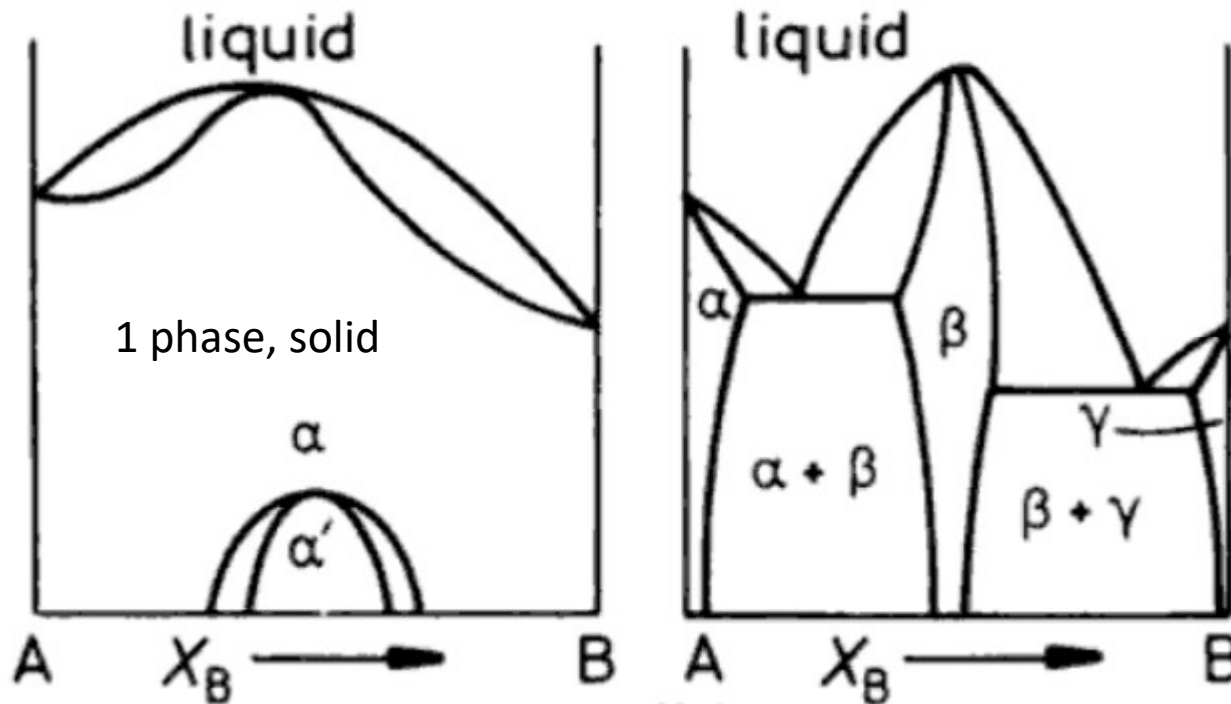
broad stability range

## Binary phase diagrams : Ordered phases

$$\Delta H_{\text{MIX}} < 0$$

Peak in liquidus line : attraction between atoms

*i.e. A and B attract*



Weak attraction

Strong attraction

Ordered phase  $\alpha$

Ordered  $\beta$  phase extends  
to liquid phase

# Binary phase diagrams : Simple Eutectic systems

$\Delta H_{MIX} \neq 0$  ; A and B have different crystal structures

